

FIG. 2

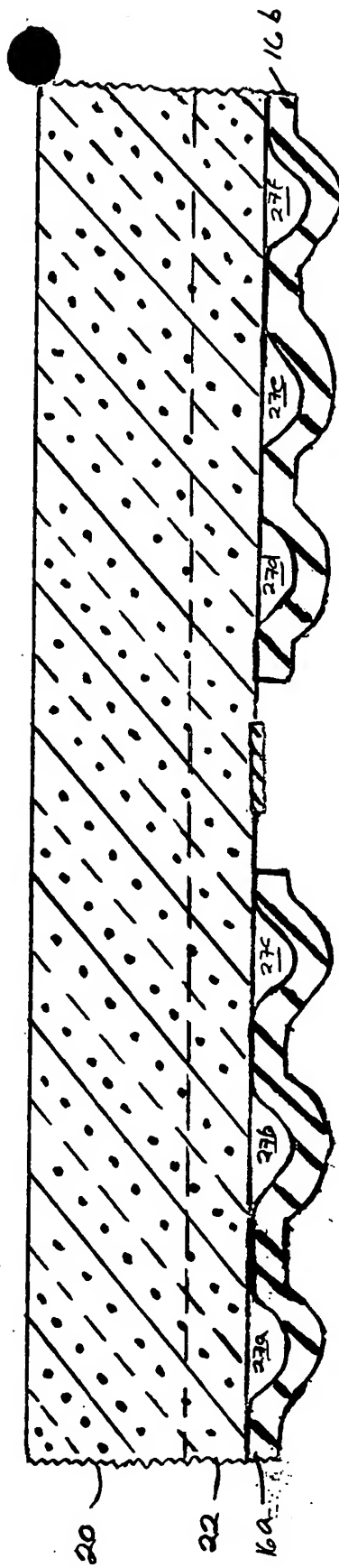
[illegible]

FIG. 3

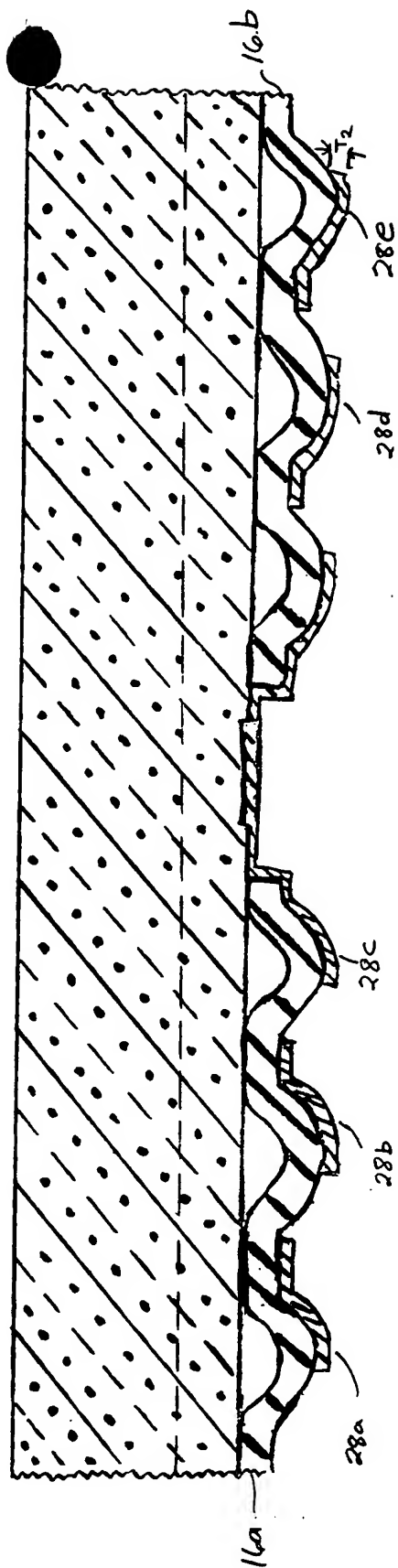


FIG. 4

FOOT THEE

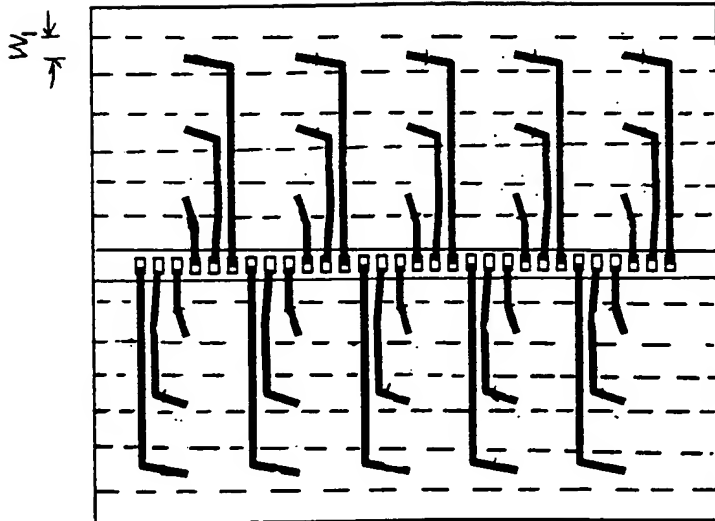


FIG. 4A

↑
Q-
↓

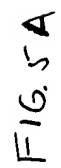


FIG. 5A

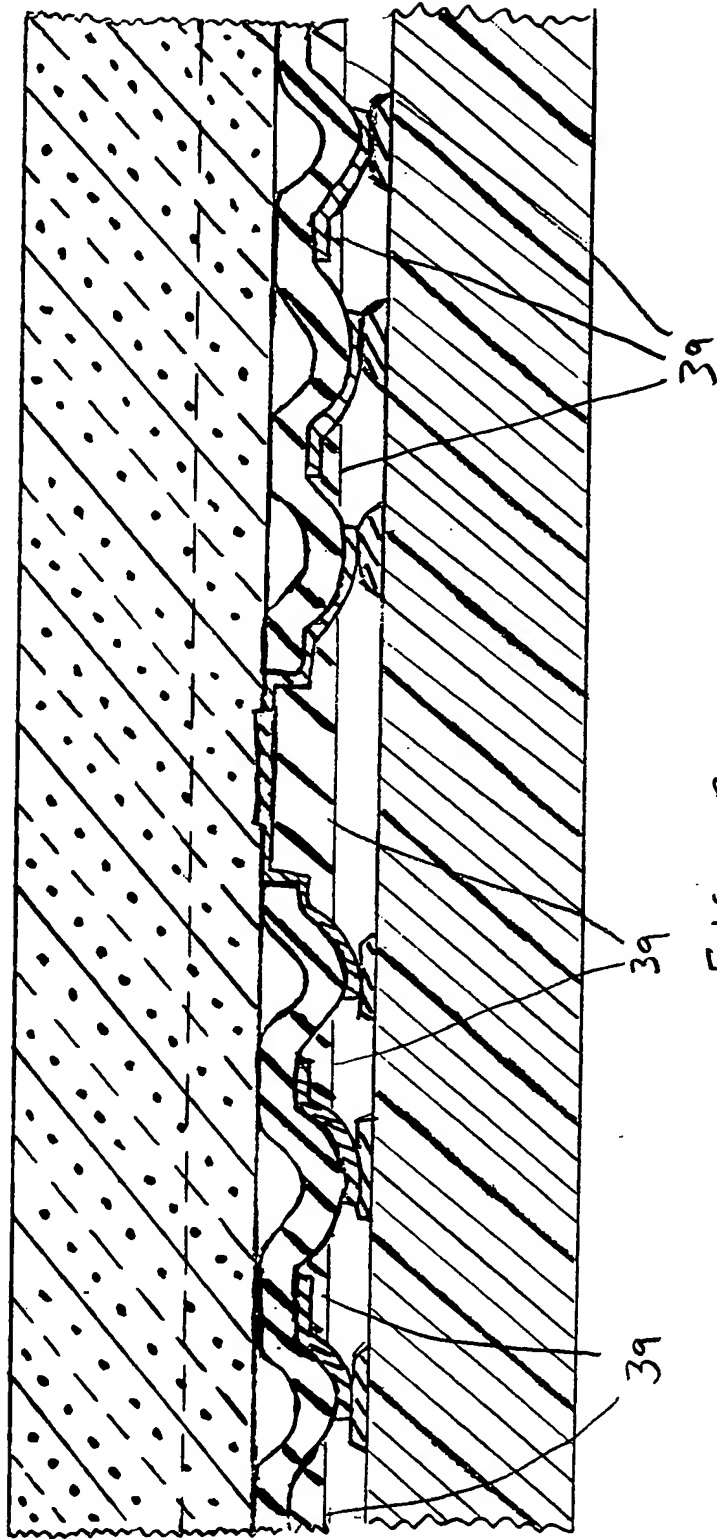


FIG. 5B

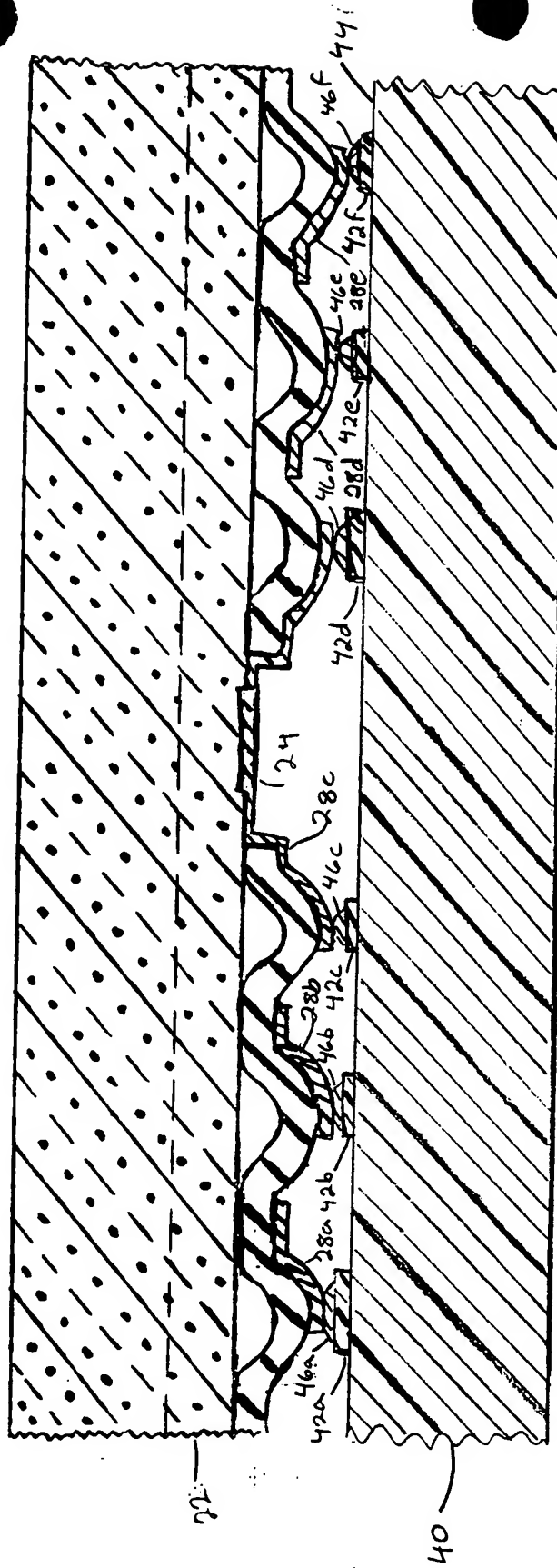


Fig. 9

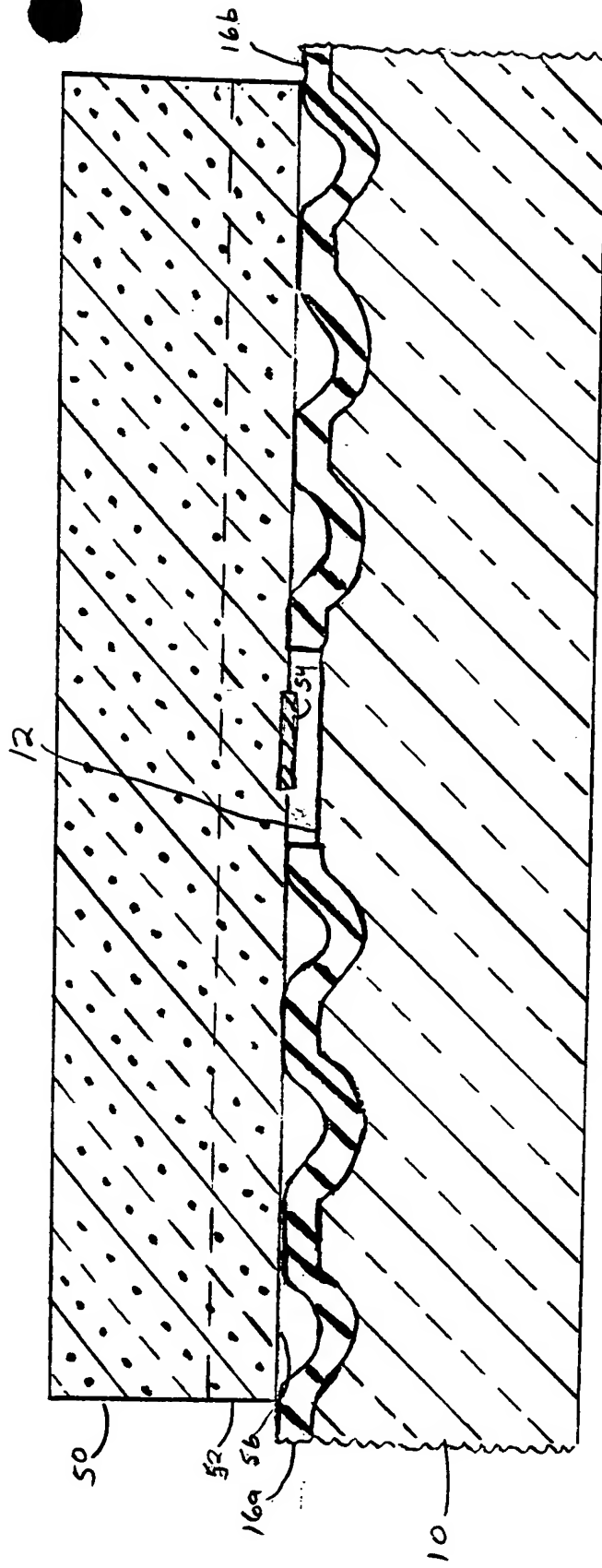


FIG. 7

FOOT" THE FOOT

$\rightarrow D_2 \leftarrow$

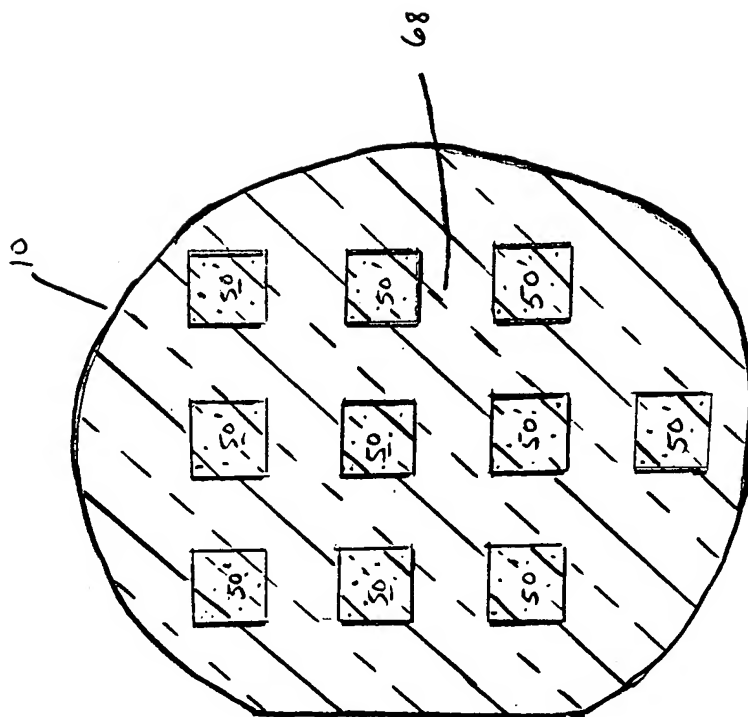


FIG. 7A

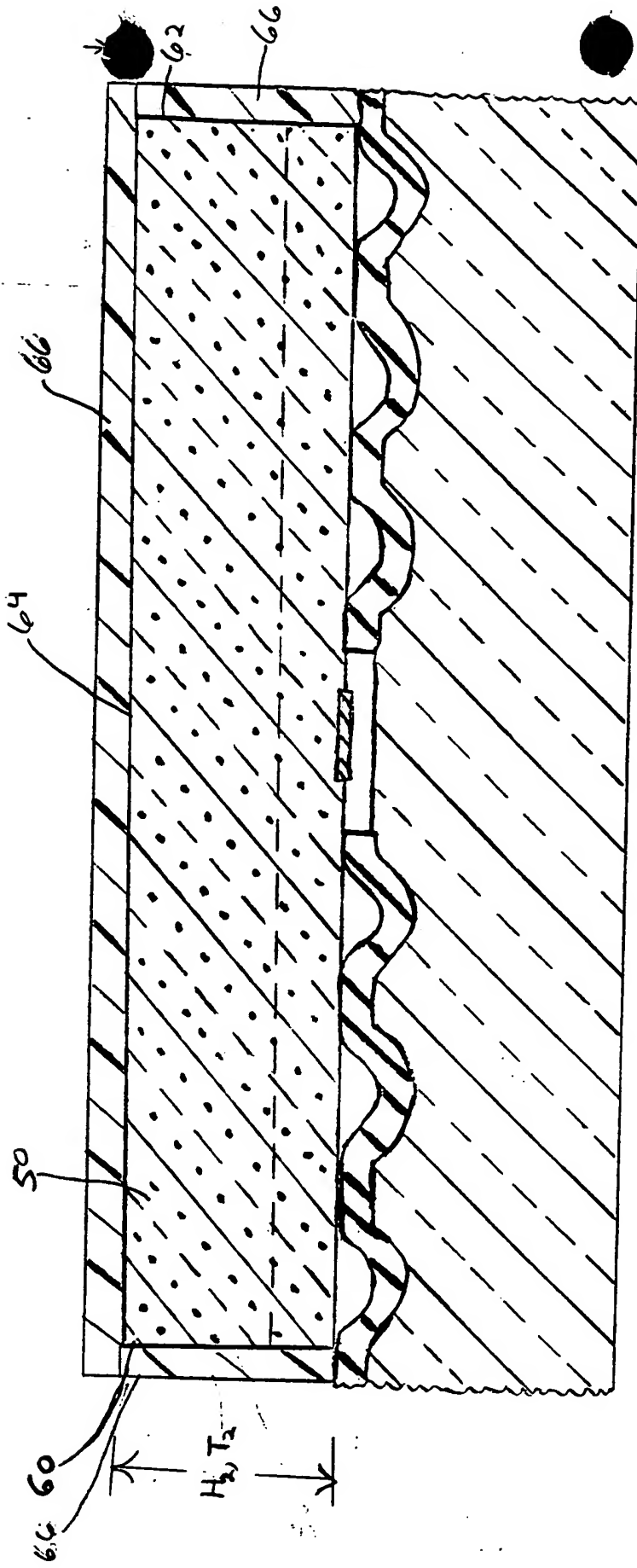


FIG. 8

FIG. 9

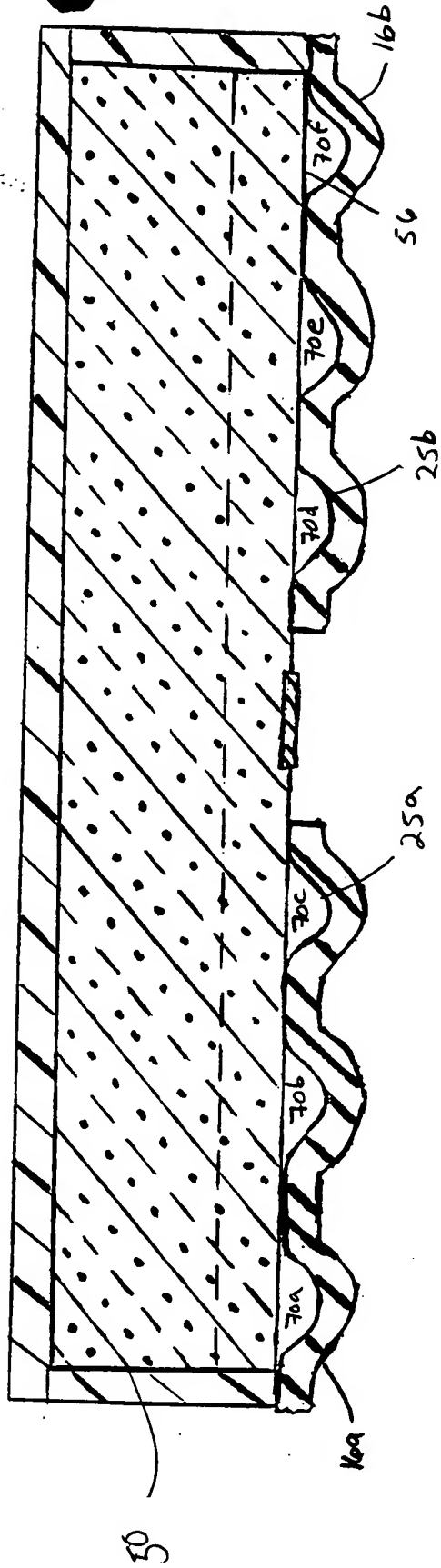


FIG. 9

FOR THE FOOT

$\rightarrow D_2 \leftarrow$

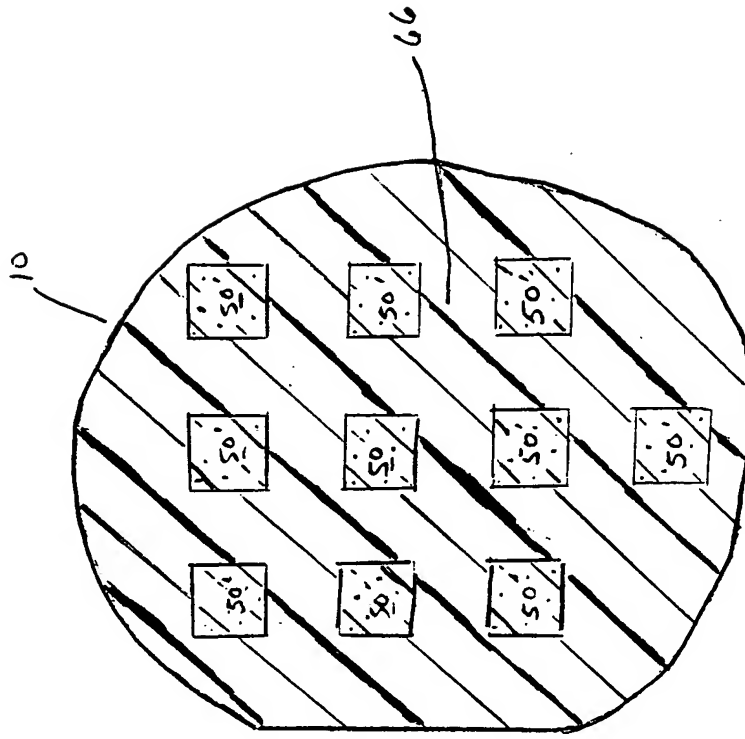


FIG. 9A

FOOT" THE FOOT

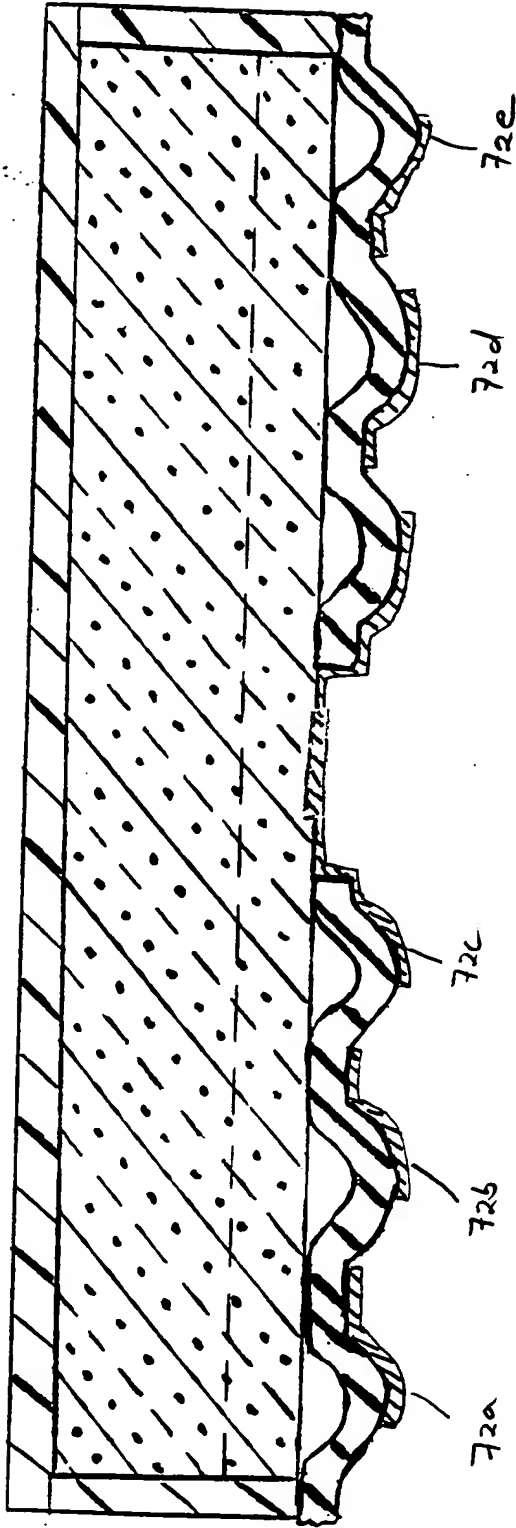


FIG. 10

FIG. 10A

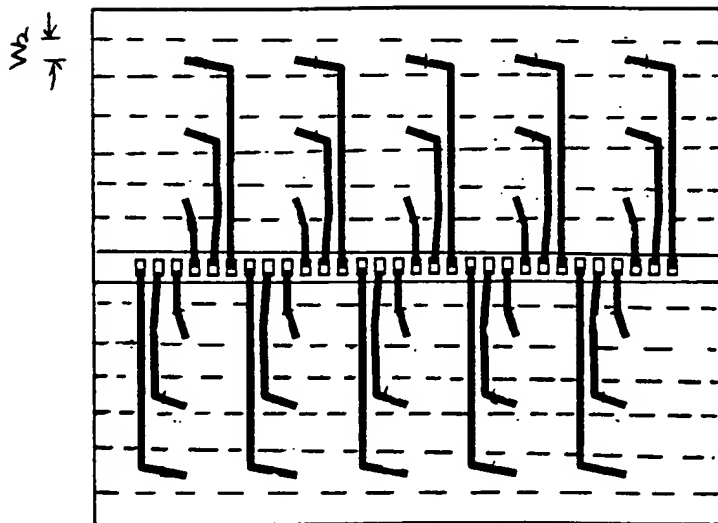


FIG. 10A

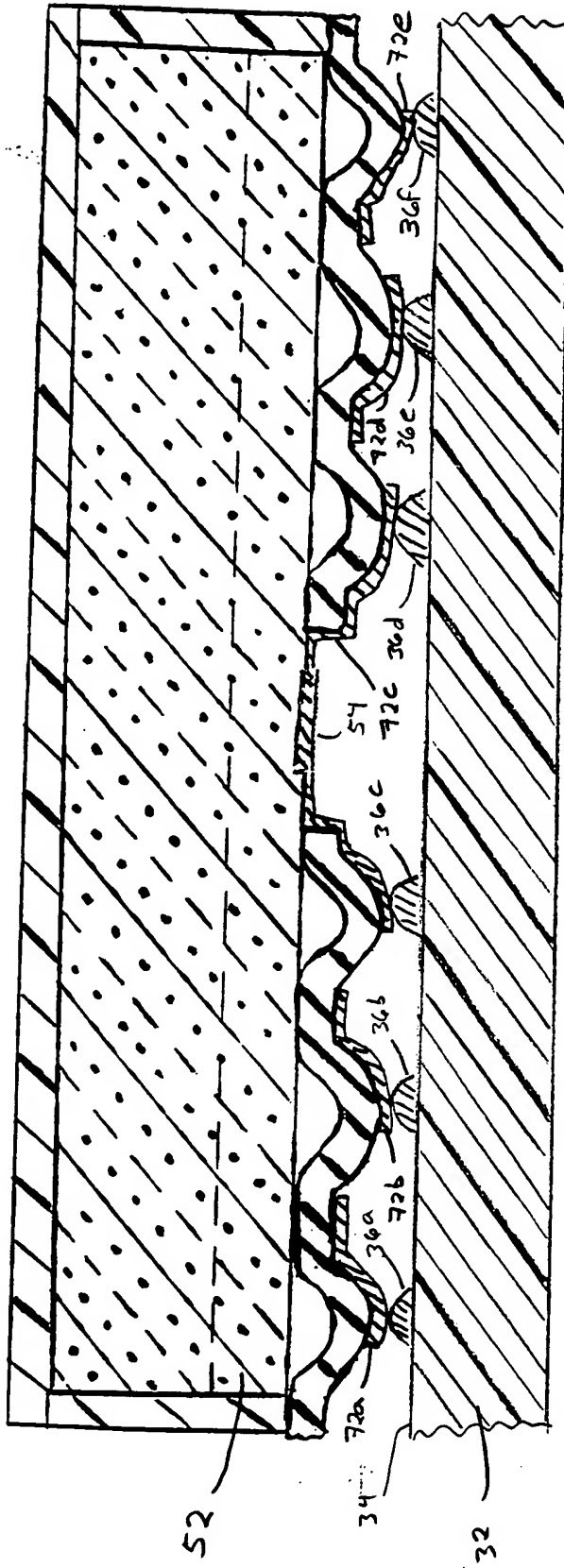


FIG. 11

$\Delta \rho = 0$



Fig. 12

FOOT THE FOOT

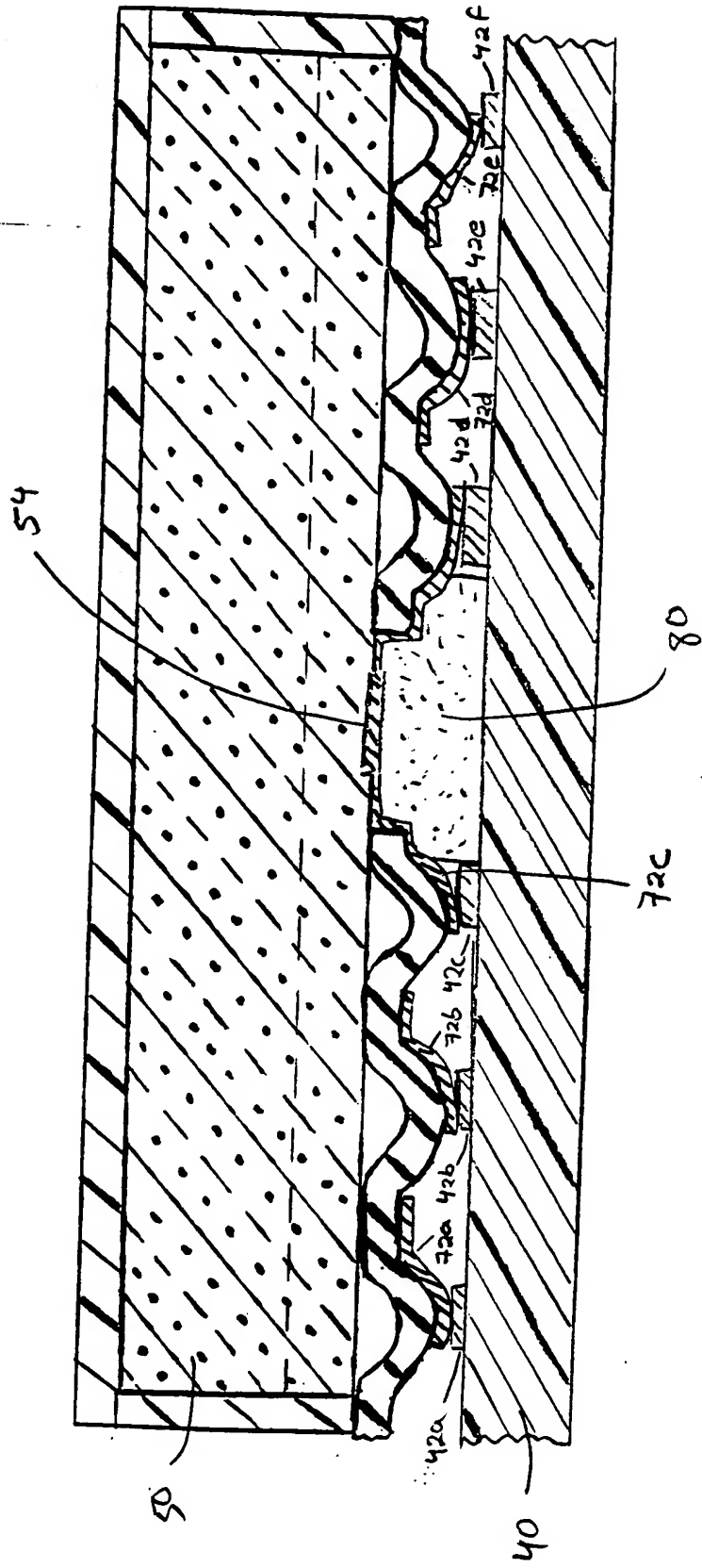


FIG. 13